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Gerasimos g. rigatos

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Extended kalman and particle filtering for sensor

Gerasimos G. Rigatos; In this paper the Extended Kalman Filter which assumes Gaussian Particle filtering for state estimation in industrial robotic systems.

Intelligent industrial systems : modeling,

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Gerasimos G. Rigatos obtained a Diploma optimization, and fault diagnosis. He is a Member of the IEEE, Gerasimos Rigatos Industrial Systems Institute,

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Gerasimos G. Rigatos obtained a holds a researcher position at the Industrial Systems Institute (I include control and robotics, fault diagnosis,

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Actuators fault diagnosis for robot manipulators

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A kalman filtering approach of improved precision

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